

Satisfiability Checking

Gomory Cuts

Prof. Dr. Erika Ábrahám

RWTH Aachen University
Informatik 2
LuFG Theory of Hybrid Systems

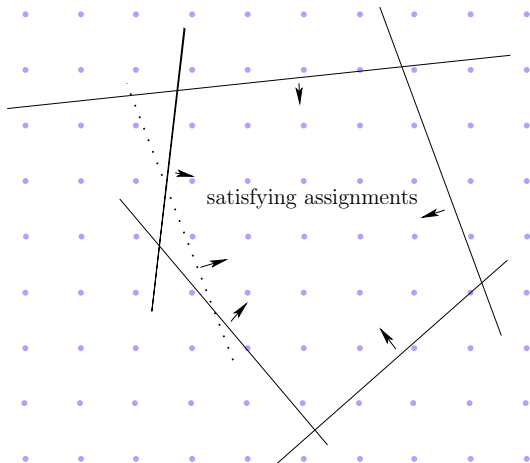
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We use **Simplex** to find a real solution. If the solution is **not integer-valued**, we generate a **new constraint** such that the new (reduced) feasible region has two important properties:

- It **does not contain the found non-integer solution** any more.
- It still **contains all feasible solutions** to the original ILP problem.

- We looked at branching by dividing the value domain of an integer variable into two halves (branching).
- We could also cut with other, better constraints.
- E.g., for $x \in \mathbb{Z}$, from $2x \leq 11$ we can conclude $x \leq 5$.
- But how to generate such cutting planes?
- We look at one method for generating cutting planes: **Gomory cuts**.

Cutting planes, geometrically



The dotted line is a cutting plane.

Example: Gomory cuts

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- The final tableau of the general Simplex algorithm includes the constraint

$$x_3 = 0.5x_1 + 2.5x_2$$

- and the solution α is

$$\{x_3 \mapsto 1.75, x_1 \mapsto 1, x_2 \mapsto 0.5\}$$

with $1.75 = 0.5 \cdot 1 + 2.5 \cdot 0.5$.

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- Subtracting these values from the variables gives us

$$x_3 - 1.75 = 0.5(x_1 - 1) + 2.5(x_2 - 0.5) .$$

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- This constraint is unsatisfied by α because $\alpha(x_1) = 1$ and $\alpha(x_2) = 0.5$.
- Hence, this constraint **removes the current solution**.
- On the other hand, it is implied by the integer system of constraints, and hence **cannot remove any integer** solution.

- Generalizing this example:
 - Upper bounds.
 - Both positive and negative coefficients.
- The description that follows is based on
 - *Integrating Simplex with DPLL(T)*
Technical report SRI-CSL-06-01
Dutertre and de Moura (2006).

There are two preliminary conditions for deriving a Gomory cut from a constraint:

- The assignment to at least one basic or original variable is fractional.
- The non-basic variables are either additional variables or their coefficients are integers.
- One more constraint which we discuss later.

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- Consider the i -th constraint

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with $x_i \in \mathcal{B}$, $\alpha(x_i)$ not an integer and a_{ij} integer for all $j \in \mathcal{N}_o$.

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$$x_i - \underbrace{\sum_{x_j \in \mathcal{N}_o} a_{ij} x_j}_T = \sum_{x_j \in \mathcal{N}_a} a_{ij} x_j$$

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- Since α is a solution,

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Assumption: $\alpha(T)$ is not an integer.

- We have

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- Then also

$$T - \alpha(T) = \sum_{j \in \mathcal{N}_a} a_{ij} (x_j - \alpha(x_j))$$

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- It follows that

$$f_T + \sum_{j \in \mathcal{N}_a} a_{ij} (x_j - \alpha(x_j))$$

should be integer-valued. **Note:** $0 < f_T < 1$.

- Partition the non-basic additional variables to
 - those that are currently assigned their lower bound, and
 - those that are currently assigned their upper bound:

$$\begin{aligned}L &= \{j \mid x_j \in \mathcal{N}_a \wedge \alpha(x_j) = l_j\} \\U &= \{j \mid x_j \in \mathcal{N}_a \wedge \alpha(x_j) = u_j\} .\end{aligned}$$

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- We further split L and U as follows:

$$\begin{aligned}L^+ &= \{j \mid j \in L \wedge a_{ij} > 0\} \\L^- &= \{j \mid j \in L \wedge a_{ij} < 0\} \\U^+ &= \{j \mid j \in U \wedge a_{ij} > 0\} \\U^- &= \{j \mid j \in U \wedge a_{ij} < 0\}\end{aligned}$$

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- and further equals

$$\begin{aligned} f_T &+ \sum_{j \in L^+} a_{ij}(x_j - l_j) + \sum_{j \in L^-} a_{ij}(x_j - l_j) \\ &- \sum_{j \in U^-} a_{ij}(u_j - x_j) - \sum_{j \in U^+} a_{ij}(u_j - x_j) \end{aligned}$$

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■ Then

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positive and integer-valued, thus

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■ Gathering the positive components,

$$\sum_{j \in L^+} a_{ij}(x_j - l_j) - \sum_{j \in U^-} a_{ij}(u_j - x_j) \geq 1 - f_T,$$

or, equivalently,

$$\sum_{j \in L^+} \frac{a_{ij}}{1 - f_T}(x_j - l_j) - \sum_{j \in U^-} \frac{a_{ij}}{1 - f_T}(u_j - x_j) \geq 1.$$

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■ Gathering the negative components,

$$\sum_{j \in L^-} a_{ij}(x_j - l_j) - \sum_{j \in U^+} a_{ij}(u_j - x_j) \leq -f_T .$$

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■ Dividing by $-f_T$ gives us

$$- \sum_{j \in L^-} \frac{a_{ij}}{f_T}(x_j - l_j) + \sum_{j \in U^+} \frac{a_{ij}}{f_T}(u_j - x_j) \geq 1 .$$

- Case 1: $\sum_{j \in L} a_{ij}(x_j - l_j) - \sum_{j \in U} a_{ij}(u_j - x_j) > 0$:

$$\sum_{j \in L^+} \frac{a_{ij}}{1 - f_T}(x_j - l_j) - \sum_{j \in U^-} \frac{a_{ij}}{1 - f_T}(u_j - x_j) \geq 1.$$

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- Therefore these two equations imply (note that all sums-blocks are non-negative)

$$\begin{aligned} & \sum_{j \in L^+} \frac{a_{ij}}{1 - f_T}(x_j - l_j) - \sum_{j \in L^-} \frac{a_{ij}}{f_T}(x_j - l_j) \\ & + \sum_{j \in U^+} \frac{a_{ij}}{f_T}(u_j - x_j) - \sum_{j \in U^-} \frac{a_{ij}}{1 - f_T}(u_j - x_j) \geq 1. \end{aligned}$$

$$\sum_{j \in L^+} \frac{a_{ij}}{1 - f_T} (x_j - l_j) - \sum_{j \in L^-} \frac{a_{ij}}{f_T} (x_j - l_j) \\ + \sum_{j \in U^+} \frac{a_{ij}}{f_T} (u_j - x_j) - \sum_{j \in U^-} \frac{a_{ij}}{1 - f_T} (u_j - x_j) \geq 1.$$

- Since each of the elements on the left-hand side is equal to zero under the current assignment α , this assignment α is ruled out by the new constraint.
- In other words: the solution to the linear problem augmented with the constraint is guaranteed to be **different from the previous one**.