

Satisfiability Checking

Gauß and Fourier-Motzkin Variable Elimination
for Linear Real Arithmetic

Prof. Dr. Erika Ábrahám

RWTH Aachen University
Informatik 2
LuFG Theory of Hybrid Systems

WS 19/20

The Xmas problem

There are three types of Xmas presents Santa Claus can make.

- Santa Claus wants to reduce the overhead by making only two types.
- He needs at least 100 presents.
- He needs at least 5 of either type 1 or type 2.
- He needs at least 10 of the third type.
- Each present of type 1, 2, and 3 need 1, 2, resp. 5 minutes to make.
- Santa Claus is late, and he has only 3 hours left.
- Each present of type 1, 2, and 3 costs 3, 2, resp. 1 EUR.
- He has 300 EUR for presents in total.

The Xmas problem

There are three types of Xmas presents Santa Claus can make.

- Santa Claus wants to reduce the overhead by making only two types.
- He needs at least 100 presents.
- He needs at least 5 of either type 1 or type 2.
- He needs at least 10 of the third type.
- Each present of type 1, 2, and 3 need 1, 2, resp. 5 minutes to make.
- Santa Claus is late, and he has only 3 hours left.
- Each present of type 1, 2, and 3 costs 3, 2, resp. 1 EUR.
- He has 300 EUR for presents in total.

$$\begin{aligned} & (p_1 = 0 \vee p_2 = 0 \vee p_3 = 0) \wedge p_1 + p_2 + p_3 \geq 100 \wedge \\ & (p_1 \geq 5 \vee p_2 \geq 5) \wedge p_3 \geq 10 \wedge p_1 + 2p_2 + 5p_3 \leq 180 \wedge \\ & \qquad \qquad \qquad 3p_1 + 2p_2 + p_3 \leq 300 \end{aligned}$$

Quantifier-free linear real arithmetic (QFLRA)

Quantifier-free linear real arithmetic (QFLRA)

Linear real arithmetic is the first-order theory with signature $\{0, 1, +, <\}$ and the domain being the reals \mathbb{R} .

Quantifier-free linear real arithmetic (QFLRA)

Linear real arithmetic is the first-order theory with signature $\{0, 1, +, <\}$ and the domain being the reals \mathbb{R} .

Syntax of linear real arithmetic

Terms: $t ::= 0 \mid 1 \mid x \mid t + t$

Constraints: $c ::= t < t$

Formulas: $\varphi ::= c \mid \neg\varphi \mid \varphi \wedge \varphi \mid \exists x. \varphi$

where x stands for a variable.

Quantifier-free linear real arithmetic (QFLRA)

Linear real arithmetic is the first-order theory with signature $\{0, 1, +, <\}$ and the domain being the reals \mathbb{R} .

Syntax of linear real arithmetic

Terms:	$t ::= 0$		1		x		$t + t$
Constraints:	$c ::= t < t$						
Formulas:	$\varphi ::= c$		$\neg\varphi$		$\varphi \wedge \varphi$		$\exists x. \varphi$

where x stands for a variable.

- Syntactic sugar for constraints: $t_1 \leq t_2$, $t_1 = t_2$, $t_1 \neq t_2$.

Quantifier-free linear real arithmetic (QFLRA)

Linear real arithmetic is the first-order theory with signature $\{0, 1, +, <\}$ and the domain being the reals \mathbb{R} .

Syntax of linear real arithmetic

Terms:	$t ::= 0$		1		x		$t + t$
Constraints:	$c ::= t < t$						
Formulas:	$\varphi ::= c$		$\neg\varphi$		$\varphi \wedge \varphi$		$\exists x. \varphi$

where x stays for a variable.

- Syntactic sugar for constraints: $t_1 \leq t_2$, $t_1 = t_2$, $t_1 \neq t_2$.
- The semantics is standard.

Quantifier-free linear real arithmetic (QFLRA)

Linear real arithmetic is the first-order theory with signature $\{0, 1, +, <\}$ and the domain being the reals \mathbb{R} .

Syntax of linear real arithmetic

Terms:	$t ::= 0$		1		x		$t + t$
Constraints:	$c ::= t < t$						
Formulas:	$\varphi ::= c$		$\neg\varphi$		$\varphi \wedge \varphi$		$\exists x. \varphi$

where x stays for a variable.

- Syntactic sugar for constraints: $t_1 \leq t_2$, $t_1 = t_2$, $t_1 \neq t_2$.
- The semantics is standard.
- Linear real arithmetic is also called [linear real algebra](#).

Quantifier-free linear real arithmetic (QFLRA)

Linear real arithmetic is the first-order theory with signature $\{0, 1, +, <\}$ and the domain being the reals \mathbb{R} .

Syntax of linear real arithmetic

Terms:	$t ::= 0$		1		x		$t + t$
Constraints:	$c ::= t < t$						
Formulas:	$\varphi ::= c$		$\neg\varphi$		$\varphi \wedge \varphi$		$\exists x. \varphi$

where x stays for a variable.

- Syntactic sugar for constraints: $t_1 \leq t_2$, $t_1 = t_2$, $t_1 \neq t_2$.
- The semantics is standard.
- Linear real arithmetic is also called **linear real algebra**.
- We consider the **satisfiability problem for the quantifier-free fragment QFLRA** (or equivalently the existential fragment, i.e., no universal quantifiers and no negation of expressions containing existential quantifiers).

Gauß variable elimination (based on equations)

Reminder: In an SMT solver for QFLRA, the theory solver needs to check the satisfiability of sets of constraints $\sum_{k=1}^N a_{ik} \cdot x_k \sim_i b_i$, where $a_{i,k}$ and b_i are integer (or rational) constants, x_k are real-valued variables, and $\sim_i \in \{=, \leq, <\}$ for $k=1, \dots, N$ and $i=1, \dots, M$. (Note: $t > b$ is equivalent to $-t < -b$ and similarly for \geq .)

Gauß variable elimination (based on equations)

Reminder: In an SMT solver for QFLRA, the theory solver needs to check the satisfiability of sets of constraints $\sum_{k=1}^N a_{ik} \cdot x_k \sim_i b_i$, where $a_{i,k}$ and b_i are integer (or rational) constants, x_k are real-valued variables, and $\sim_i \in \{=, \leq, <\}$ for $k=1, \dots, N$ and $i=1, \dots, M$. (Note: $t > b$ is equivalent to $-t < -b$ and similarly for \geq .)

- Assume that the i th constraint is an equation with $a_{ij} \neq 0$ for some $1 \leq j \leq N$:

$$\sum_{k=1}^N a_{ik} \cdot x_k = b_i \quad (a_{i,k}, b_i: \text{integer/rational constants}, x_k: \text{variables})$$

Gauß variable elimination (based on equations)

Reminder: In an SMT solver for QFLRA, the theory solver needs to check the satisfiability of sets of constraints $\sum_{k=1}^N a_{ik} \cdot x_k \sim_i b_i$, where $a_{i,k}$ and b_i are integer (or rational) constants, x_k are real-valued variables, and $\sim_i \in \{=, \leq, <\}$ for $k=1, \dots, N$ and $i=1, \dots, M$. (Note: $t > b$ is equivalent to $-t < -b$ and similarly for \geq .)

- Assume that the i th constraint is an equation with $a_{ij} \neq 0$ for some $1 \leq j \leq N$:

$$\sum_{k=1}^N a_{ik} \cdot x_k = b_i \quad (a_{i,k}, b_i: \text{integer/rational constants}, x_k: \text{variables})$$

$$\Rightarrow a_{ij} \cdot x_j = b_i - \sum_{k \in \{1, \dots, j-1, j+1, \dots, N\}} a_{ik} \cdot x_k$$

Gauß variable elimination (based on equations)

Reminder: In an SMT solver for QFLRA, the theory solver needs to check the satisfiability of sets of constraints $\sum_{k=1}^N a_{ik} \cdot x_k \sim_i b_i$, where $a_{i,k}$ and b_i are integer (or rational) constants, x_k are real-valued variables, and $\sim_i \in \{=, \leq, <\}$ for $k=1, \dots, N$ and $i=1, \dots, M$. (Note: $t > b$ is equivalent to $-t < -b$ and similarly for \geq .)

- Assume that the i th constraint is an equation with $a_{ij} \neq 0$ for some $1 \leq j \leq N$:

$$\sum_{k=1}^N a_{ik} \cdot x_k = b_i \quad (a_{i,k}, b_i: \text{integer/rational constants}, x_k: \text{variables})$$

$$\Rightarrow a_{ij} \cdot x_j = b_i - \sum_{k \in \{1, \dots, j-1, j+1, \dots, N\}} a_{ik} \cdot x_k$$

$$\Rightarrow x_j = \frac{b_i}{a_{ij}} - \sum_{k \in \{1, \dots, j-1, j+1, \dots, N\}} \frac{a_{ik}}{a_{ij}} \cdot x_k := \beta_j$$

Gauß variable elimination (based on equations)

Reminder: In an SMT solver for QFLRA, the theory solver needs to check the satisfiability of sets of constraints $\sum_{k=1}^N a_{ik} \cdot x_k \sim_i b_i$, where $a_{i,k}$ and b_i are integer (or rational) constants, x_k are real-valued variables, and $\sim_i \in \{=, \leq, <\}$ for $k=1, \dots, N$ and $i=1, \dots, M$. (Note: $t > b$ is equivalent to $-t < -b$ and similarly for \geq .)

- Assume that the i th constraint is an equation with $a_{ij} \neq 0$ for some $1 \leq j \leq N$:

$$\sum_{k=1}^N a_{ik} \cdot x_k = b_i \quad (a_{i,k}, b_i: \text{integer/rational constants}, x_k: \text{variables})$$

$$\Rightarrow a_{ij} \cdot x_j = b_i - \sum_{k \in \{1, \dots, j-1, j+1, \dots, N\}} a_{ik} \cdot x_k$$

$$\Rightarrow x_j = \frac{b_i}{a_{ij}} - \sum_{k \in \{1, \dots, j-1, j+1, \dots, N\}} \frac{a_{ik}}{a_{ij}} \cdot x_k := \beta_j$$

- Replace x_j by β_j in all constraints (and multiply the involved constraints by a_{ij} if integer coefficients are wanted).

Gauß variable elimination (based on equations)

Reminder: In an SMT solver for QFLRA, the theory solver needs to check the satisfiability of sets of constraints $\sum_{k=1}^N a_{ik} \cdot x_k \sim_i b_i$, where $a_{i,k}$ and b_i are integer (or rational) constants, x_k are real-valued variables, and $\sim_i \in \{=, \leq, <\}$ for $k=1, \dots, N$ and $i=1, \dots, M$. (Note: $t > b$ is equivalent to $-t < -b$ and similarly for \geq .)

- Assume that the i th constraint is an equation with $a_{ij} \neq 0$ for some $1 \leq j \leq N$:

$$\sum_{k=1}^N a_{ik} \cdot x_k = b_i \quad (a_{i,k}, b_i: \text{integer/rational constants}, x_k: \text{variables})$$

$$\Rightarrow a_{ij} \cdot x_j = b_i - \sum_{k \in \{1, \dots, j-1, j+1, \dots, N\}} a_{ik} \cdot x_k$$

$$\Rightarrow x_j = \frac{b_i}{a_{ij}} - \sum_{k \in \{1, \dots, j-1, j+1, \dots, N\}} \frac{a_{ik}}{a_{ij}} \cdot x_k := \beta_j$$

- Replace x_j by β_j in all constraints (and multiply the involved constraints by a_{ij} if integer coefficients are wanted).
- After removing tautologies, this [substitution](#) leads to an equisatisfiable problem with (at most) $M - 1$ constraints in (at most) $N - 1$ variables (at least the i th constraint and x_j are eliminated).

What remains to be solved

- Let us assume first that after applying Gauß variable elimination as long as possible, m non-strict inequalities in n variables are left (i.e., there are no strict inequalities):

$$\bigwedge_{1 \leq i \leq m} \sum_{1 \leq j \leq n} a_{ij} x_j \leq b_i$$

What remains to be solved

- Let us assume first that after applying Gauß variable elimination as long as possible, m non-strict inequalities in n variables are left (i.e., there are no strict inequalities):

$$\bigwedge_{1 \leq i \leq m} \sum_{1 \leq j \leq n} a_{ij} x_j \leq b_i$$

- Input in matrix form: $A\bar{x} \leq \bar{b}$

$$m \text{ constraints} \quad \begin{pmatrix} a_{11} & a_{12} & \cdots & \cdots & a_{1n} \\ a_{21} & a_{22} & \ddots & & \vdots \\ \vdots & & & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & \cdots & a_{mn} \end{pmatrix} \begin{pmatrix} x_1 \\ \vdots \\ \vdots \\ x_n \end{pmatrix} \leq \begin{pmatrix} b_1 \\ \vdots \\ \vdots \\ b_m \end{pmatrix}$$

n variables

- Earliest method for solving **linear inequality systems**:
discovered in 1826 by Fourier, re-discovered by Motzkin in 1936

- Earliest method for solving **linear inequality systems**:
discovered in 1826 by Fourier, re-discovered by Motzkin in 1936
- Basic idea of **variable elimination**:
 - Pick a variable and eliminate it, yielding an equisatisfiable formula that does not refer to the eliminated variable any more.
 - Continue until all variables are eliminated.

- Earliest method for solving **linear inequality systems**: discovered in 1826 by Fourier, re-discovered by Motzkin in 1936
- Basic idea of **variable elimination**:
 - Pick a variable and eliminate it, yielding an equisatisfiable formula that does not refer to the eliminated variable any more.
 - Continue until all variables are eliminated.
- **Fourier-Motzkin**: Collect requirements on the **lower an upper bounds** on the variable we want to eliminate.

- For a variable x_n , we can partition the constraints according to the coefficients of x_n :
 - $a_{in} = 0$: constraint i puts no bound on x_n
 - $a_{in} > 0$: constraint i puts an upper bound on x_n
 - $a_{in} < 0$: constraint i puts a lower bound on x_n

- For a variable x_n , we can partition the constraints according to the coefficients of x_n :
 - $a_{in} = 0$: constraint i puts no bound on x_n
 - $a_{in} > 0$: constraint i puts an upper bound on x_n
 - $a_{in} < 0$: constraint i puts a lower bound on x_n

$$\sum_{j=1}^n a_{ij} \cdot x_j \leq b_i$$

- For a variable x_n , we can partition the constraints according to the coefficients of x_n :
 - $a_{in} = 0$: constraint i puts no bound on x_n
 - $a_{in} > 0$: constraint i puts an upper bound on x_n
 - $a_{in} < 0$: constraint i puts a lower bound on x_n

$$\sum_{j=1}^n a_{ij} \cdot x_j \leq b_i$$

$$\Rightarrow a_{in} \cdot x_n \leq b_i - \sum_{j=1}^{n-1} a_{ij} \cdot x_j$$

- For a variable x_n , we can partition the constraints according to the coefficients of x_n :
 - $a_{in} = 0$: constraint i puts no bound on x_n
 - $a_{in} > 0$: constraint i puts an upper bound on x_n
 - $a_{in} < 0$: constraint i puts a lower bound on x_n

$$\sum_{j=1}^n a_{ij} \cdot x_j \leq b_i$$

$$\Rightarrow a_{in} \cdot x_n \leq b_i - \sum_{j=1}^{n-1} a_{ij} \cdot x_j$$

$$(a) \quad \begin{matrix} a_{in} > 0 \\ \Rightarrow \end{matrix} \quad x_n \leq \frac{b_i}{a_{in}} - \sum_{j=1}^{n-1} \frac{a_{ij}}{a_{in}} \cdot x_j \quad \text{upper bound}$$

$$(b) \quad \begin{matrix} a_{in} < 0 \\ \Rightarrow \end{matrix} \quad x_n \geq \frac{b_i}{a_{in}} - \sum_{j=1}^{n-1} \frac{a_{ij}}{a_{in}} \cdot x_j \quad \text{lower bound}$$

Example for upper and lower bounds

Category for x_1 ?

$$(1) \quad x_1 - x_2 \leq 0$$

$$(2) \quad x_1 - x_3 \leq 0$$

$$(3) \quad -x_1 + x_2 + 2x_3 \leq 0$$

$$(4) \quad -x_3 \leq -1$$

Example for upper and lower bounds

- (1) $x_1 - x_2 \leq 0$
- (2) $x_1 - x_3 \leq 0$
- (3) $-x_1 + x_2 + 2x_3 \leq 0$
- (4) $-x_3 \leq -1$

Category for x_1 ?

Upper bound

Example for upper and lower bounds

- (1) $x_1 - x_2 \leq 0$
- (2) $x_1 - x_3 \leq 0$
- (3) $-x_1 + x_2 + 2x_3 \leq 0$
- (4) $-x_3 \leq -1$

Category for x_1 ?

Upper bound

Upper bound

Example for upper and lower bounds

	Category for x_1 ?
(1) $x_1 - x_2 \leq 0$	Upper bound
(2) $x_1 - x_3 \leq 0$	Upper bound
(3) $-x_1 + x_2 + 2x_3 \leq 0$	Lower bound
(4) $-x_3 \leq -1$	

Example for upper and lower bounds

	Category for x_1 ?
(1) $x_1 - x_2 \leq 0$	Upper bound
(2) $x_1 - x_3 \leq 0$	Upper bound
(3) $-x_1 + x_2 + 2x_3 \leq 0$	Lower bound
(4) $-x_3 \leq -1$	No bound

Eliminating unbounded variables

- Iteratively remove variables that are not bounded in both ways (and all the constraints that use them).
- The new problem has a solution iff the old problem has one!

$$\begin{aligned}-8x + 7y &\leq 0 \\ -x &\leq -3 \\ -y + z &\leq 0 \\ -z &\leq -10 \\ z &\leq 20\end{aligned}$$

Eliminating unbounded variables

- Iteratively remove variables that are not bounded in both ways (and all the constraints that use them).
- The new problem has a solution iff the old problem has one!

$$\begin{array}{rcl} \cancel{-8x + 7y} & \leq & \cancel{0} \\ \cancel{-x} & \leq & \cancel{3} \\ -y + z & \leq & 0 \\ -z & \leq & -10 \\ z & \leq & 20 \end{array}$$

Eliminating unbounded variables

- Iteratively remove variables that are not bounded in both ways (and all the constraints that use them).
- The new problem has a solution iff the old problem has one!

$$\begin{array}{rcl} \cancel{-8x + 7y} & \leq & \cancel{0} \\ \cancel{-x} & \leq & \cancel{3} \\ -y + z & \leq & 0 \\ -z & \leq & -10 \\ z & \leq & 20 \end{array} \quad \longrightarrow \quad \begin{array}{rcl} -y + z & \leq & 0 \\ -z & \leq & -10 \\ z & \leq & 20 \end{array}$$

Eliminating unbounded variables

- Iteratively remove variables that are not bounded in both ways (and all the constraints that use them).
- The new problem has a solution iff the old problem has one!

$$\begin{array}{r} \cancel{-8x + 7y \leq 0} \\ \cancel{-x \leq 3} \\ -y + z \leq 0 \\ -z \leq -10 \\ z \leq 20 \end{array} \quad \longrightarrow \quad \begin{array}{r} \cancel{y + z \leq 0} \\ -z \leq -10 \\ z \leq 20 \end{array}$$

Eliminating unbounded variables

- Iteratively remove variables that are not bounded in both ways (and all the constraints that use them).
- The new problem has a solution iff the old problem has one!

$$\begin{array}{r} \cancel{-8x + 7y \leq 0} \\ \cancel{-x \leq 3} \\ -y + z \leq 0 \\ -z \leq -10 \\ z \leq 20 \end{array} \quad \longrightarrow \quad \begin{array}{r} \cancel{y + z \leq 0} \\ -z \leq -10 \\ z \leq 20 \end{array} \quad \longrightarrow \quad \begin{array}{r} -z \leq -10 \\ z \leq 20 \end{array}$$

- For each pair of a lower bound β_l and an upper bound β_u , we have

$$\beta_l \leq x_n \leq \beta_u$$

- For each pair of a lower bound β_l and an upper bound β_u , we have

$$\beta_l \leq x_n \leq \beta_u$$

- For each such pair, add the constraint

$$\beta_l \leq \beta_u$$

Category for x_1 ?

$$(1) \quad x_1 - x_2 \leq 0$$

$$(2) \quad x_1 - x_3 \leq 0$$

$$(3) \quad -x_1 + x_2 + 2x_3 \leq 0$$

$$(4) \quad -x_3 \leq -1$$

- (1) $x_1 - x_2 \leq 0$
 - (2) $x_1 - x_3 \leq 0$
 - (3) $-x_1 + x_2 + 2x_3 \leq 0$
 - (4) $-x_3 \leq -1$
-

Category for x_1 ?

Upper bound

Upper bound

Lower bound

eliminate x_1

$$(1) \quad x_1 - x_2 \leq 0$$

$$(2) \quad x_1 - x_3 \leq 0$$

$$(3) \quad -x_1 + x_2 + 2x_3 \leq 0$$

$$(4) \quad -x_3 \leq -1$$

$$(5) \quad 2x_3 \leq 0 \quad \text{(from 1,3)}$$

Category for x_1 ?

Upper bound

Upper bound

Lower bound

eliminate x_1

- (1) $x_1 - x_2 \leq 0$
 - (2) $x_1 - x_3 \leq 0$
 - (3) $-x_1 + x_2 + 2x_3 \leq 0$
 - (4) $-x_3 \leq -1$
-

- (5) $2x_3 \leq 0$ (from 1,3)
- (6) $x_2 + x_3 \leq 0$ (from 2,3)

Category for x_1 ?

Upper bound

Upper bound

Lower bound

eliminate x_1

Category for x_1 ?

~~(1) $x_1 - x_2 \leq 0$~~

~~(2) $x_1 - x_3 \leq 0$~~

~~(3) $x_1 + x_2 + 2x_3 \leq 0$~~

(4) $-x_3 \leq -1$

eliminate x_1

(5) $2x_3 \leq 0$ (from 1,3)

(6) $x_2 + x_3 \leq 0$ (from 2,3)

Category for x_1 ?

~~(1) $x_1 - x_2 \leq 0$~~

~~(2) $x_1 - x_3 \leq 0$~~

~~(3) $x_1 + x_2 + 2x_3 \leq 0$~~

(4) $-x_3 \leq -1$

eliminate x_1

(5) $2x_3 \leq 0$ (from 1,3)

(6) $x_2 + x_3 \leq 0$ (from 2,3)

we eliminate x_3

$$\begin{array}{l} \text{(1)} \quad x_1 - x_2 \leq 0 \\ \text{(2)} \quad x_1 - x_3 \leq 0 \\ \text{(3)} \quad x_1 + x_2 + 2x_3 \leq 0 \\ \text{(4)} \quad -x_3 \leq -1 \end{array}$$

$$\begin{array}{ll} \text{(5)} \quad 2x_3 \leq 0 & \text{(from 1,3)} \\ \text{(6)} \quad x_2 + x_3 \leq 0 & \text{(from 2,3)} \end{array}$$

Category for x_1 ?

Lower bound
eliminate x_1

Upper bound

Upper bound

we eliminate x_3

Category for x_1 ?

~~(1) $x_1 - x_2 \leq 0$~~

~~(2) $x_1 - x_3 \leq 0$~~

~~(3) $x_1 + x_2 + 2x_3 \leq 0$~~

(4) $-x_3 \leq -1$

(5) $2x_3 \leq 0$ (from 1,3)

(6) $x_2 + x_3 \leq 0$ (from 2,3)

(7) $1 \leq 0$ (from 4,5)

Lower bound

eliminate x_1

Upper bound

Upper bound

we eliminate x_3

→ **Contradiction** (the system is UNSAT)

Algorithm: satCheck (only non-strict inequalities, full lazy)

Input: Set C of non-strict linear real arithmetic inequalities over variables x_1, \dots, x_n

Output: Satisfiability of $\bigwedge_{c \in C} c$

Algorithm: satCheck (only non-strict inequalities, full lazy)

Input: Set C of non-strict linear real arithmetic inequalities over variables x_1, \dots, x_n

Output: Satisfiability of $\bigwedge_{c \in C} c$

- 1 $k := 1;$
- 2 if $k > n$ then goto 8
- 3 $C_u := \{(\sum_{j=1}^n a_j x_j \leq b) \in C \mid a_k > 0\};$
- 4 $C_l := \{(\sum_{j=1}^n a_j x_j \leq b) \in C \mid a_k < 0\};$
- 5 $C := C \setminus (C_u \cup C_l);$
- 6 $C := C \cup \left\{ \frac{b_l}{a_{lk}} - \sum_{j=k+1}^n \frac{a_{lj}}{a_{ln}} \cdot x_j \leq \frac{b_u}{a_{uk}} - \sum_{j=k+1}^n \frac{a_{uj}}{a_{un}} \cdot x_j \mid \sum_{j=1}^n a_{lj} x_j \leq b_l \in C_l \wedge \sum_{j=1}^n a_{uj} x_j \leq b_u \in C_u \right\};$
- 7 goto 2
- 8 if $\{(l \leq u) \in C \mid l > u\} = \emptyset$ then return **SAT**;
- 9 else return **UNSAT**;

Strict inequalities

The approach works also if we have both non-strict and strict inequalities.
All we need to change is that

Strict inequalities

The approach works also if we have both non-strict and strict inequalities. All we need to change is that

- we distinguish between **strict** and **non-strict** lower and upper bounds (defined by strict respectively non-strict inequalities), and
- for each pair of lower and upper bounds, if any of them is strict then we add the constraint

$$\beta_l < \beta_u$$

instead of

$$\beta_l \leq \beta_u .$$

- Question: Does this method work also for linear **integer** arithmetic, i.e., if the variables range over the integers (instead of the reals)?

Linear integer arithmetic, non-linear real arithmetic

- Question: Does this method work also for linear **integer** arithmetic, i.e., if the variables range over the integers (instead of the reals)?
- Answer: No.

- Question: Does this method work also for linear **integer** arithmetic, i.e., if the variables range over the integers (instead of the reals)?
- Answer: No.
- Reason: The integer domain is **not dense**.

- Question: Does this method work also for linear **integer** arithmetic, i.e., if the variables range over the integers (instead of the reals)?
- Answer: No.
- Reason: The integer domain is **not dense**.

- Question: Does this method work also for **non-linear** real arithmetic, i.e., if the variables range over the reals but also multiplication is allowed?

- Question: Does this method work also for linear **integer** arithmetic, i.e., if the variables range over the integers (instead of the reals)?
- Answer: No.
- Reason: The integer domain is **not dense**.

- Question: Does this method work also for **non-linear** real arithmetic, i.e., if the variables range over the reals but also multiplication is allowed?
- Answer: No.

- Question: Does this method work also for linear **integer** arithmetic, i.e., if the variables range over the integers (instead of the reals)?
- Answer: No.
- Reason: The integer domain is **not dense**.

- Question: Does this method work also for **non-linear** real arithmetic, i.e., if the variables range over the reals but also multiplication is allowed?
- Answer: No.
- Reason: in general it is not possible to transform constraints containing non-linear polynomial expressions such that we have a single variable on the left-hand-side and a real-arithmetic expression on the right-hand side (we would need complicated case distinctions, fractions and roots).

- Worst-case complexity:

$m \rightarrow$

- Worst-case complexity:

$$m \rightarrow \left(\frac{m}{2}\right)^2 = \frac{m^2}{4}$$

- Worst-case complexity:

$$\begin{aligned} m &\rightarrow \left(\frac{m}{2}\right)^2 = \frac{m^2}{4} \\ &\rightarrow \left(\frac{\frac{m^2}{4}}{2}\right)^2 = \frac{m^4}{4^3} \end{aligned}$$

- Worst-case complexity:

$$\begin{aligned} m &\rightarrow \left(\frac{m}{2}\right)^2 = \frac{m^2}{4} \\ &\rightarrow \left(\frac{\frac{m^2}{4}}{2}\right)^2 = \frac{m^4}{4^3} \\ &\rightarrow \left(\frac{\frac{m^4}{4^3}}{2}\right)^2 = \frac{m^8}{4^7} \end{aligned}$$

- Worst-case complexity:

$$\begin{aligned} m &\rightarrow \left(\frac{m}{2}\right)^2 = \frac{m^2}{4} \\ &\rightarrow \left(\frac{\frac{m^2}{4}}{2}\right)^2 = \frac{m^4}{4^3} \\ &\rightarrow \left(\frac{\frac{m^4}{4^3}}{2}\right)^2 = \frac{m^8}{4^7} \\ &\rightarrow \dots \end{aligned}$$

- Worst-case complexity:

$$\begin{aligned} m &\rightarrow \left(\frac{m}{2}\right)^2 = \frac{m^2}{4} \\ &\rightarrow \left(\frac{\frac{m^2}{4}}{2}\right)^2 = \frac{m^4}{4^3} \\ &\rightarrow \left(\frac{\frac{m^4}{4^3}}{2}\right)^2 = \frac{m^8}{4^7} \\ &\rightarrow \dots \\ &\rightarrow 4 \cdot \left(\frac{m}{4}\right)^{2^d} \end{aligned}$$

- Worst-case complexity:

$$\begin{aligned} m &\rightarrow \left(\frac{m}{2}\right)^2 = \frac{m^2}{4} \\ &\rightarrow \left(\frac{\frac{m^2}{4}}{2}\right)^2 = \frac{m^4}{4^3} \\ &\rightarrow \left(\frac{\frac{m^4}{4^3}}{2}\right)^2 = \frac{m^8}{4^7} \\ &\rightarrow \dots \\ &\rightarrow 4 \cdot \left(\frac{m}{4}\right)^{2^d} \end{aligned}$$

- Heavy!

- Worst-case complexity:

$$\begin{aligned}m &\rightarrow \left(\frac{m}{2}\right)^2 = \frac{m^2}{4} \\&\rightarrow \left(\frac{\frac{m^2}{4}}{2}\right)^2 = \frac{m^4}{4^3} \\&\rightarrow \left(\frac{\frac{m^4}{4^3}}{2}\right)^2 = \frac{m^8}{4^7} \\&\rightarrow \dots \\&\rightarrow 4 \cdot \left(\frac{m}{4}\right)^{2^d}\end{aligned}$$

- Heavy!
- The bottleneck: case-splitting

Requirements on theory solver in the SMT context

- 1 Incrementality?
- 2 Minimal infeasible subsets?
- 3 Backtracking?